# Pioneer

## 150 kHz / 38 kHz Phased-Array DVLs

Teledyne RD Instruments' 150 kHz and 38 kHz **Phased-Array Doppler Velocity** Logs (DVLs) include the industry's first DVL designed to provide precision velocity data at ranges of 500 m to greater than 2,500 m above the seafloor.

This extended range makes the Pioneer DVLs ideally suited for aiding navigation systems onboard small, medium, and large platforms where the ability to transition from the deep waters of the open oceans to the shallow environments of the littoral zone is a critical enabler.

Designed specifically with the Unmanned Underwater Vehicle (UUV) in mind, the self-contained 38 kHz has oil-filled sensors for larger, full ocean depth platforms. Additionally, these DVLs can also be leveraged for surface and submarine manned and unmanned vessels.

### **PRODUCT FEATURES**

- 1000 m depth rating and 500 to 2,500 meter bottomtracking capability for deep water operations
- Accommodates vehicles from 12-inch (32 cm) diameter up to large manned platforms
- Flexible triggering with both trigger in and trigger out
- Time of validity output for highly accurate coupling with an Inertial Navigation System (INS)
- Real-time current profiling option provides additional critical data parameters from a single instrument
- Extended Range Tracking (XRT option) provides 50% increase in bottom tracking range



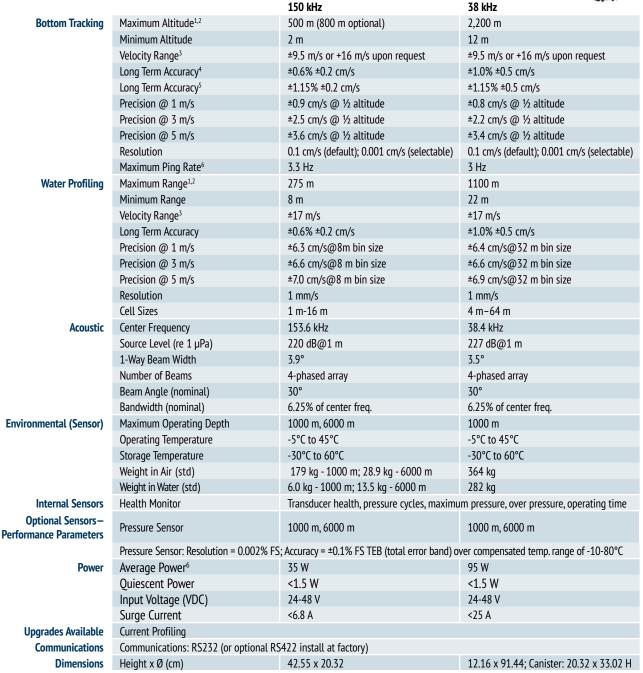
Utilizing state-of-the-art electronics, the 150 kHz and 38k Hz Pioneer DVLs provide expanded connectivity with other sensors while minimizing overall power consumption.

These powerful DVLs use Teledyne RDI's proven bottom detection algorithms and single ping bottom location capability with its Broadband velocity processing technology, providing users with highly reliable precision velocity data for navigation and position processing, even over indeterminate terrain.



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### TECHNICAL SPECIFICATIONS



1~ @5°C and 35ppt, salinity, @ max V.

2 Maximum range may be reduced due to flow noise.

3 When mounted with beam @45°. Also, for platforms with forward velocity higher than reverse (or vice versa), the maximum velocity can be increased to [-2m/s -> +16m/s] for bottom track via firmware modification.

ECCN 6A001

5 ECCN 6A991 6 Worst case at low altitude.



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